



**Micromega Corporation**

# Using the uM-FPU64 Matrix Instructions

## Introduction

The uM-FPU64 chip provides a number of instructions for operating on matrices and vectors. Matrices are defined as a group of sequential FPU registers organized by rows and columns. For example, the following diagram shows a matrix of 2 rows and 4 columns.

	Col 0	Col 1	Col 2	Col 3
Row 0	0, 0	0, 1	0, 2	0, 3
Row 1	1, 0	1, 1	1, 2	1, 3

Matrices are stored in sequential 32-bit floating point registers, or in RAM in row major order. The following list shows the storage locations for a matrix of 2 rows and 4 columns starting at register 16.

Register 16	row 0, column 0
Register 17	row 0, column 1
Register 18	row 0, column 2
Register 19	row 0, column 3
Register 20	row 1, column 0
Register 21	row 1, column 1
Register 22	row 1, column 2
Register 23	row 1, column 3

## Instruction Summary

The FPU has several special purpose instructions for working with matrices and vectors.

SELECTMA	Select matrix A
SELECTMB	Select matrix B
SELECTMC	Select matrix C
LOADMA	Load register 0 with value from matrix A
LOADMB	Load register 0 with value from matrix B
LOADMC	Load register 0 with value from matrix C
SAVEMA	Save register 0 value to matrix A
SAVEMB	Save register 0 value to matrix B
SAVEMC	Save register 0 value to matrix C
MOP	Matrix Operations

Since matrices and vectors are stored in FPU registers, any FPU instructions that reference registers can also be used to access values in a matrix or vector. Register X can be used for sequential access.

## Matrix Operations

Matrix operations can involve one, two or three matrices which are referred to as MA, MB and MC. The **SELECTMA**, **SELECTMB** and **SELECTMC** instructions are used to select the registers that define a matrix. The starting register, the number of rows, and the number of columns are specified following the opcode. For example, the following instruction selects MB as a matrix with 2 rows and 4 columns starting at register 16.

```
SELECTMB, 16, 2, 4
```

Register X is also set to the first register of the matrix by the **SELECTMA**, **SELECTMB**, and **SELECTMC** instructions. This makes it easy to use any of the register X instructions to quickly access the sequential registers in the matrix (e.g. **READX**, **WRITEX**, **XSAVE**, **LOADX**, etc.). The elements in a matrix can be accessed directly by using the specific register address for each element, or they can be accessed by row and column number using the **LOADMA**, **LOADMB**, **LOADMC**, **SAVEMA**, **SAVEMB** and **SAVEMC** instructions.

The **LOADMA**, **LOADMB** and **LOADMC** instructions load register 0 with the value from a selected element in the matrix. The following instruction loads register 0 with the value in row 1, column 2 of matrix MB (row and columns numbers start at 0).

```
LOADMB, 1, 2
```

The **SAVEMA**, **SAVEMB** and **SAVEMC** instructions store the value in register 0 to the selected element in the matrix. The following instruction saves the value in register 0 to row 1, column 2 of matrix MB.

```
SAVEMB, 1, 2
```

## MOP instruction

The MOP (matrix operation) instruction performs all the matrix operations.

### Scalar Operations

A scalar operation takes the single value in register 0 and applies it to each element of the matrix MA. For example, the Scalar Add operation using two 2x2 matrices, will perform the following:

```
MA[0, 0] = MA[0, 0] + reg[0]
MA[0, 1] = MA[0, 1] + reg[0]
MA[1, 0] = MA[1, 0] + reg[0]
MA[1, 1] = MA[1, 1] + reg[0]
```

Operation	Instruction	Description
Scalar Set	MOP, SCALAR_SET	MA[row, col] = reg[0]
Scalar Add	MOP, SCALAR_ADD	MA[row, col] = MA[row, col] + reg[0]
Scalar Subtract	MOP, SCALAR_SUB	MA[row, col] = MA[row, col] - reg[0]
Scalar Subtract (reverse)	MOP, SCALAR_SUBR	MA[row, col] = reg[0] - MA[r,c]
Scalar Multiply	MOP, SCALAR_MUL	MA[r,c] = MA[row, col] * reg[0]
Scalar Divide	MOP, SCALAR_DIV	MA[row, col] = MA[row, col] / reg[0]
Scalar Divide (reverse)	MOP, SCALAR_DIVR	MA[row, col] = reg[0] / MA[r,c]
Scalar Power	MOP, SCALAR_POW	MA[r,c] = MA[row, col] ** reg[0]

### Element-wise Operations

An Element-wise operation performs each operation on corresponding elements of matrix MA and MB. For example, the Element-wise Add operation using two 2x2 matrices, will perform the following:

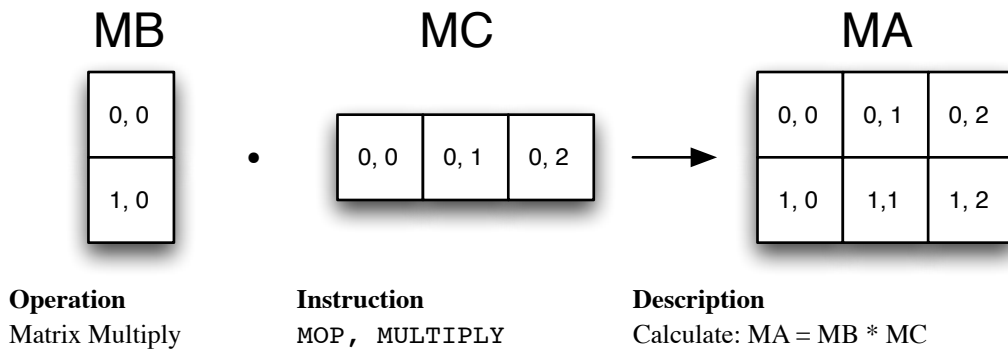
```
MA[0, 0] = MA[0, 0] + MB[0, 0]
MA[0, 1] = MA[0, 1] + MB[0, 1]
```

$MA[1, 0] = MA[1, 0] + MB[1, 0]$   
 $MA[1, 1] = MA[1, 1] + MB[1, 1]$

Operation	Instruction	Description
Element-wise Set	MOP, EWISE_SET	$MA[\text{row}, \text{col}] = MB[\text{row}, \text{col}]$
Element-wise Add	MOP, EWISE_ADD	$MA[\text{row}, \text{col}] = MA[\text{row}, \text{col}] + MB[\text{row}, \text{col}]$
Element-wise Subtract	MOP, EWISE_SUB	$MA[\text{row}, \text{col}] = MA[\text{row}, \text{col}] - MB[\text{row}, \text{col}]$
Element-wise Subtract (reverse)	MOP, EWISE_SUBR	$MA[\text{row}, \text{col}] = MB[\text{row}, \text{col}] - MA[\text{row}, \text{col}]$
Element-wise Multiply	MOP, EWISE_MUL	$MA[\text{row}, \text{col}] = MA[\text{row}, \text{col}] * MB[\text{row}, \text{col}]$
Element-wise Divide	MOP, EWISE_DIV	$MA[\text{row}, \text{col}] = MA[\text{row}, \text{col}] / MB[\text{row}, \text{col}]$
Element-wise Divide (reverse)	MOP, EWISE_DIVR	$MA[r,c] = MB[\text{row}, \text{col}] / MA[r,c]$
Element-wise Power	MOP, EWISE_POW	$MA[\text{row}, \text{col}] = MA[\text{row}, \text{col}] ** MB[\text{row}, \text{col}]$

### Matrix Multiplication

The matrix multiplication performs a matrix multiply of MB times MC and stores the result in MA. The number of columns in MB must be the same as the number of rows in MC, or the multiply will not be done. The size of matrix MA will be updated to reflect the rows and columns of the resulting matrix.



### Identity and Diagonal Matrix

The identity operation stores the value 1.0 in all elements of matrix MA where the row and column numbers are the same, and stores 0.0 in all other elements. The following diagram shows 3x3 identity matrix:

	Col 0	Col 1	Col 2
Row 0	1.0	0.0	0.0
Row 1	0.0	1.0	0.0
Row 2	0.0	0.0	1.0

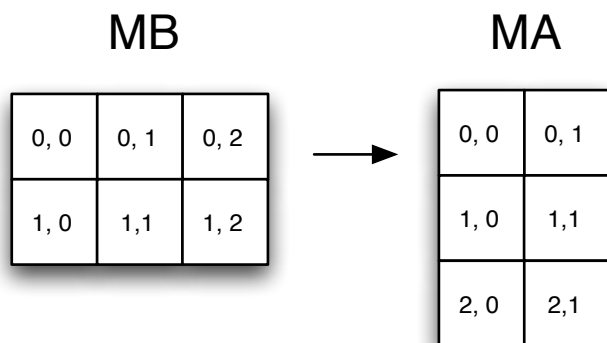
The diagonal operation stores the value contained in register 0 in all elements of matrix MA where the row and column numbers are the same, and stores 0.0 in all other elements.

Operation	Instruction	Description
Identity matrix	MOP, IDENTITY	MA = identity matrix
Diagonal matrix	MOP, DIAGONAL	MA = diagonal matrix

## Transpose

The transpose operation turns rows into columns and columns into rows. The following diagram shows the transpose of a 2x3 array to a 3x2 array. The size of matrix MA will be updated to reflect the rows and columns of the resulting matrix.

Operation	Instruction	Description
Transpose	MOP, TRANSPOSE	MA = transpose matrix



## Statistics

The statistical operations provide a fast way of calculating values for a group of registers. The following example calculates the average value of registers 16 to 31.

```
SELECTMA, 16, 16, 1  
MOP, AVE
```

select MA as a 16x1 vector starting at register 16  
calculate average value of elements in MA

Operation	Instruction	Description
Count	MOP, COUNT	reg[0] = count of all elements in MA
Sum	MOP, SUM	reg[0] = sum of all elements in MA
Average	MOP, AVE	reg[0] = average of all elements in MA
Minimum	MOP, MIN	reg[0] = minimum of all elements in MA
Maximum	MOP, MAX	reg[0] = maximum of all elements in MA

## Matrix copy

The copy operations provide a convenient way to copy the contents of one matrix to another. The size of the destination matrix will be updated to reflect the rows and columns of the resulting matrix. If there is not sufficient space at the destination, the copy will not be done.

Operation	Instruction	Description
Copy Matrix A to Matrix B	MOP, COPY_AB	Matrix B is set to a copy of matrix A.
Copy Matrix A to Matrix C	MOP, COPY_AC	Matrix C is set to a copy of matrix A.
Copy Matrix B to Matrix A	MOP, COPY_BA	Matrix A is set to a copy of matrix B.
Copy Matrix B to Matrix C	MOP, COPY_BC	Matrix C is set to a copy of matrix B.
Copy Matrix C to Matrix A	MOP, COPY_CA	Matrix A is set to a copy of matrix C.
Copy Matrix C to Matrix B	MOP, COPY_CB	Matrix B is set to a copy of matrix C.

## Matrix Determinant

The determinant operation is only valid for 2x2 and 3x3 matrices. It returns the determinant in register 0. To calculate the determinant of larger matrices use the LU decomposition or Cholesky decomposition matrix

operations.

Instruction	Description
MOP, DETERM	reg[0] = determinant of MA

### Matrix Inverse

The inverse operation is only valid for 2x2 and 3x3 matrices. Matrix MA is set to the inverse of matrix MB. To calculate the inverse of larger matrices use the LU decomposition or Cholesky decomposition matrix operations.

Instruction	Description
MOP, INVERSE	MA = inverse of MA

### Load Registers to Matrix

The load register to matrix instructions can be used to quickly load a matrix by copying register values to a matrix. The byte immediately following the matrix operation specifies the number of index values to follow. An index value is a signed 8-bit integer specifying one of the registers from 0 to 127. If the index is positive, the value of the indexed register is copied to the matrix. If the index is negative, the absolute value is used as an index, and the negative value of the indexed register is copied to the matrix. Register 0 is cleared to zero before the register values are copied, so index 0 will always store a zero value in the matrix. The values are stored sequentially, beginning with the first register in the destination matrix.

Instruction	Description
MOP, LOAD_RA, <i>byteCount</i> , <i>byte</i> , ...	Load matrix A from registers.
MOP, LOAD_RB, <i>byteCount</i> , <i>byte</i> , ...	Load matrix B from registers.
MOP, LOAD_RC, <i>byteCount</i> , <i>byte</i> , ...	Load matrix C from registers.

### Example:

Suppose you wanted to create a 2-dimensional rotation matrix as follows:

cos A	-sin A
sin A	cos A

Assuming register 1 contains the value sin A, and register 2 contains the value cos A, the following instructions create the matrix.

SELECTMA, 10, 2, 2	select MA as a 2x2 matrix starting at register 10
MOP, LOAD_RA, 4, 2, -1, 1, 2	create the rotation matrix

### Load Matrix to Matrix

The load matrix to matrix instructions can be used to quickly copy values from one matrix to another. The byte immediately following the matrix operation specifies the number of index values to follow. An index value is a signed 8-bit integer specifying the offset of the desired matrix element from the start of the matrix. If the index is positive, the matrix element is copied to matrix MA. If the index is negative, the absolute value is used as an index, and the negative value of the matrix element is copied to the destination matrix. Register 0 is cleared to zero before the register values are copied, so index 0 will always store a zero value in matrix MA. The values are stored sequentially, beginning with the first register in matrix MA.

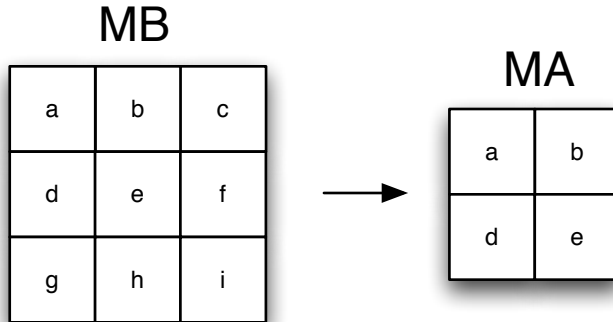
**Instruction**`MOP, LOAD_BA, byteCount, byte, ...``MOP, LOAD_CA, byteCount, byte, ...`**Description**

Load matrix A from matrix B.

Load matrix A from matrix C.

**Example:**

Suppose MB is a 3x3 array and you want to create a 2x2 array from the upper left corner as follows:

`SELECTMB, 20, 2, 2``MOP, LOAD_BA, 4, 0, 1, 3, 4`

select MB as a 2x2 matrix starting at register 20

copy the 2x2 subset from MA

**Save Matrix A to Register**

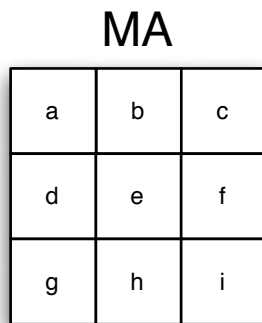
The save matrix to register instructions can be used to quickly extract values from a matrix. The byte immediately following the matrix operation specifies the number of index values to follow. An index value is a signed 8-bit integer specifying one of the registers from 0 to 127. The values are stored sequentially, beginning with the first element in matrix MA. If the index is positive, the matrix value is copied to the indexed register. If the index is negative, the matrix value is not copied.

**Instruction**`MOP, SAVE_AR, byteCount, byte, ...`**Description**

Save matrix A values to specified registers

**Example:**

Suppose matrix MA is a 3x3 matrix containing the following values:



The following instruction stores the value a to register 10, e to register 11 and i to register 12.

`MOP, SAVE_AR, 9, 10, -1, -1, -1, 11, -1, -1, -1, 12`

save matrix A values to registers

**Save Matrix to Matrix**

The save matrix to matrix instructions can be used to quickly extract values from a matrix. The byte immediately following the matrix operation specifies the number of index values to follow. An index value is a signed 8-bit integer specifying the offset of the desired matrix element from the start of matrix MA. The values are stored

sequentially in the destination matrix, beginning with the first element in matrix MA. If the index is positive, the matrix value is copied to the destination matrix. If the index is negative, the matrix value is not copied.

#### Instruction

MOP, SAVE\_AB, *byteCount*, *byte*, ...

MOP, SAVE\_AC, *byteCount*, *byte*, ...

#### Description

Save matrix A values to matrix B

Save matrix A values to matrix C

### LU and Cholesky Decomposition

The LU and Cholesky decomposition operations can be used to calculate a matrix inverse, matrix determinant, and to solve sets of linear equations for  $n \times n$  matrices of any size. The maximum size of matrix will be limited by the available registers or RAM for storing the matrices. An augmented matrix is created by the MOP, LU\_DECOMP and MOP, CH\_DECOMP instructions. When allocating matrix storage for matrix C prior to using these instructions, this additional space must be taken into account.

**Original  $n \times n$  matrix**

0, 0	0, 1	0, 2	0, 3	0, 4
1, 0	1, 1	1, 2	1, 3	1, 4
2, 0	2, 1	2, 2	2, 3	2, 4
3, 0	3, 1	3, 2	3, 3	3, 4
4, 0	4, 1	4, 2	4, 3	4, 4

**Augmented  $n+2 \times n$  matrix**

0, 0	0, 1	0, 2	0, 3	0, 4
1, 0	1, 1	1, 2	1, 3	1, 4
2, 0	2, 1	2, 2	2, 3	2, 4
3, 0	3, 1	3, 2	3, 3	3, 4
4, 0	4, 1	4, 2	4, 3	4, 4
5, 0	5, 1	5, 2	5, 3	5, 4
6, 0	6, 1	6, 2	6, 3	6, 4

CH\_INVERSE stores  
result in  $n \times n$  elements

Input vector stored in row  $n$  for  
LU\_SOLVE and CH\_SOLVE

Solution vector returned in row  $n$   
for LU\_SOLVE and CH\_SOLVE

*Examples:*      `SELECTMC, 10, 5, 5`      Select Matrix C  
                  *fill matrix with data*

`MOP, CH_DECOMP`      Calculate Cholesky Inverse Matrix  
                  `MOP, CH_INVERSE`

## Further Information

See the Micromega website (<http://www.micromegacorp.com>) for additional information regarding the uM-FPU64 floating point coprocessor, including:

*uM-FPU64 Datasheet*  
*uM-FPU64 Instruction Set*